ER180-4-3200



ER180-4-3200,

Maxium payload 180 kg with maxium reach 3160 mm.

■ Highlights

Thanks to the excellent stiffness of the robot with sufficient arm span and high-speed intelligent palletization process package, the takt is improved by 15%, bring customers more efficiency;

Multiple specific application software could be integrated, with soft PLC and a variety of field bus interface, which enable customers easily face various application challenges;



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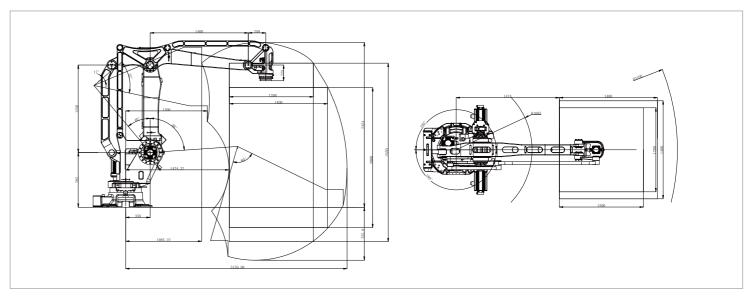
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SPECIFICATIONS

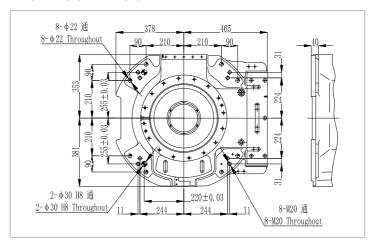
| Model | | ER180-4-3200 |
|----------------------------|------------------------|-----------------------------------|
| Туре | | Articulated |
| Controlled axes | | 4 Axes |
| Max. payload on wrist | | 180 kg |
| Repeatability | | ±0.1 mm |
| Robot weight | | 1350 kg |
| Reach | | 3160 mm |
| Robot IP grade | | IP54/ IP65 (Optional) |
| Cabinet IP grade | | IP54 |
| Installation enviroment | Ambient temperature | 0~45 °C |
| | Ambient humidity | RH≤80% (No dew nor frost allowed) |
| | Vibration acceleration | 4.9 m/s ² (<0.5 G) |

| Drive mode | | AC servo drive |
|-----------------------------------|-------|--------------------|
| Installation | | Floor, Wall |
| Allowable load moment at wrist | J 4 | 190 N·m |
| Allowable load inertia at wrist | J 4 | 56.6 kg⋅m² |
| Maximum speed | J1 | 104°/sec |
| | J2 | 104°/sec |
| | 13 | 104°/sec |
| | J 4 | 210°/sec |
| | J1 | ±180° |
| | J2 | +40°/-86° |
| Motion range | 13 | +60°/-52° |
| | J 4 | ±360° |
| | J2+J3 | -106°<(J2+J3)<+23° |

OPERATING SPACE



BASE MOUNTING SIZE



END FLANGE MOUNTING SIZE

