# ER230-2700

### ER230-2700,

Maxium payload 230 kg with maxium reach 2702 mm.

### Highlights

A brand new heavy-duty platform product, with all shafts connected by rigid gears, providing superior torque performance for the robot wrist; The robot's repeated positioning accuracy has been improved by 50%, which belongs to the leading level in the same level and can cope with various high-precision application scenarios;

Combining high rigidity transmission design with advanced trajectory algorithms, it has stronger dynamic performance and more stable high-speed operation.

### Applications

It can be used in Spot welding, SW-Stud welding, handling operations, cell changing disc and group disc, palletizing, assembling, grinding, polishing, etc.

### Industries

Suitable for auto, Lithium battery, photovoltaic, food and beverage, building materials, logistics and warehousing and other industries.

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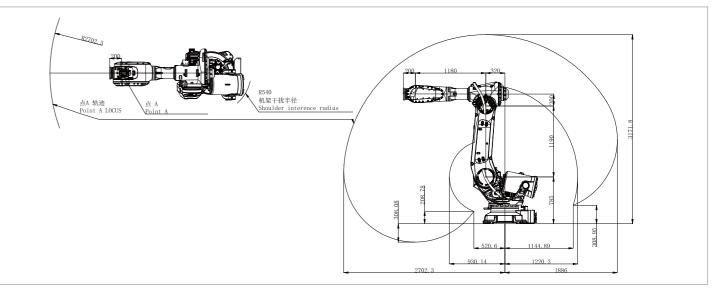
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## **EFORT**

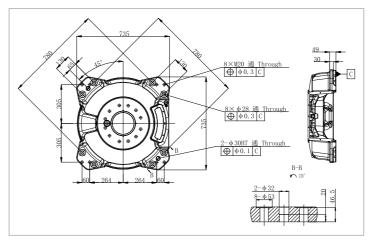
### **SPECIFICATIONS**

Model		ER230-2700	Allowable load moment at wrist	J 4	1400 N•m
Туре		Articulated		J 5	1400 N•m
1764		Articulated		J 6	745 N•m
Controlled axes		6 Axes	Allowable load inertia at wrist	J 4	180 kg•m²
Max. payload on wrist		230 kg		J 5	180 kg•m²
Repeatability		±0.05 mm		J 6	85 kg·m²
Dahatwaiaht			Maximum speed	J1	130°/sec
Robot weight		1320 kg		J 2	110°/sec
Reach		2702 mm		J 3	115°/sec
Robot IP grade		IP65		J 4	170%sec
Cabinet IP grade		1254		J 5	120°/sec
Sublict in Brude		11.54		J 6	220°/sec
Drive mode		AC servo drive		J1	±185°
Installation		Floor		J 2	+65°/-85°
Installation enviroment	Ambient temperature	0∼45 °C	Motion range	J 3	+180°/-70°
	Ambient			J 4	±360°
	humidity	RH≤80%(No dew nor frost allowed)		J 5	±130°
	Vibration acceleration	4.9 m/s <sup>2</sup> (<0.5 G)		J 6	±360°

### **OPERATING SPACE**



### **BASE MOUNTING SIZE**

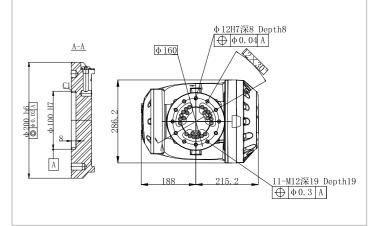


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### EFORT Intelligent Robot Co., Ltd.

PHONE: (00 86) 400-052-8877 ADDRESS: No.96 East Wanchun Road, China(Anhui) Pilot Free Trade Zone Wuhu Area, Wuhu, Anhui Province, China WWW.EFORT.COM.CN





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